

RIEGL VUX-240[®]

- **laser pulse repetition rate up to 1.8 MHz**
- **measurement rate up to 1,500,000 meas./sec**
- **scan speed up to 400 lines/second**
- **operating flight altitude up to 1,400m / 4,600 ft**
- **Field of View up to 75°**
- **perfectly linear and parallel scan lines**
- **cutting edge RIEGL technology providing:**
 - echo signal digitization
 - multiple target capability
 - online waveform processing
 - multiple-time-around processing
- **compact & lightweight**
- **easily mountable to unmanned platforms (UAVs) and to helicopters, gyrocopters, and other small manned aircrafts**
- **mechanical and electrical interface for INS/GNSS integration (optional)**
- **interfaces for up to 4 optional cameras**
- **scan data storage on internal 1 TByte SSD Memory**

The *RIEGL VUX-240* is a lightweight airborne laser scanner, especially designed for use on UAS/UAV/RPAS and small manned aeroplanes or helicopters.

With its wide field of view of 75 degrees and an extremely fast data acquisition rate of up to 1.8 MHz, the instrument is perfectly suited for high point density corridor mapping applications.

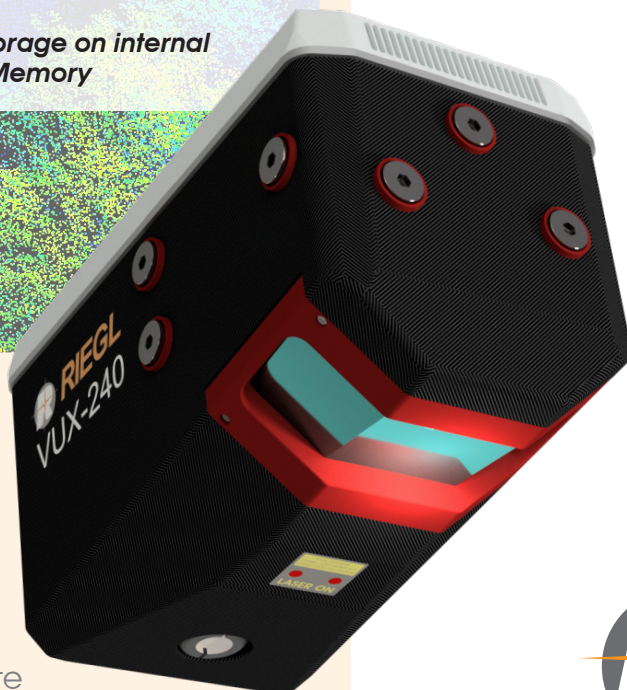
The VUX-240 makes use of *RIEGL's* unique Waveform-LiDAR technology, allowing echo digitization and online waveform processing. Multi-target resolution is the basis for penetrating even dense foliage.

A continuously rotating polygon mirror wheel enables scan speeds of up to 400 lines per second, for efficiently covering large areas when operated from fast UAVs or aircrafts.

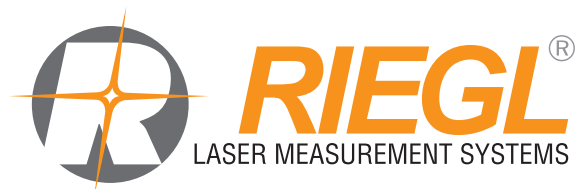
The scanner provides an internal data storage capacity of 1 TByte and is equipped with interfaces for an external IMU/GNSS system as well as to control up to four external cameras. WLAN enables direct access to the laser scanner for changing configuration settings and checking the system status.

Typical applications include

- **Corridor Mapping:
Power Line, Railway Track and Pipeline Inspection**
- **Topography in Open-Cast Mining**
- **Surveying of Urban Environments**
- **Archeology and Cultural Heritage Documentation**
- **Agriculture & Forestry**



visit our website
www.riegl.com



Technical Data *RIEGL* VUX®-240

Laser Product Classification

NOHD (Nominal Ocular Hazard Distance)

ENOH (Extended Nominal Ocular Hazard Distance)

Range Measurement Performance

Measuring Principle

Class 3R Laser Product according to IEC60825-1:2014

The following clause applies for instruments delivered into the United States: Complies with 21 CFR 1040.10 and 1040.11 except for conformance with IEC 60825-1 Ed.3., as described in Laser Notice No. 56, dated May 8, 2019.

0.3 m

2.5 m

INVISIBLE LASER RADIATION
AVOID DIRECT EYE EXPOSURE
CLASS 3R LASER PRODUCT

MAX. AVERAGE OUTPUT <15 mW
PULSE DURATION APPROX. 3 ns
WAVELENGTH 1550 nm
STANDARD IEC60825-1:2014

time of flight measurement, echo signal digitization, multiple target capability, online waveform processing, multiple-time-around-processing

Laser Pulse Repetition Rate PRR ¹⁾	150 kHz	300 kHz	600 kHz	1200 kHz	1800 kHz
Max. Measuring Range ^{2) 3)}					
natural targets $\rho \geq 20\%$	1200 m	850 m	650 m	450 m	350 m
natural targets $\rho \geq 60\%$	1900 m	1400 m	1050 m	750 m	650 m
natural targets $\rho \geq 80\%$	2150 m	1600 m	1200 m	850 m	700 m
Max. Operating Flight Altitude AGL ^{2) 4)}					
@ $\rho \geq 20\%$	900 m (2950 ft)	600 m (1950 ft)	500 m (1650 ft)	350 m (1150 ft)	250 m (800 ft)
@ $\rho \geq 60\%$	1400 m (4600 ft)	1050 m (3450 ft)	900 m (2950 ft)	550 m (1800 ft)	500 m (1650 ft)
Max. Number of Targets per Pulse ⁵⁾	15	15	15	8	5

1) Rounded average PRR.
2) Typical values for average conditions and average ambient brightness. In bright sunlight, the max. range is shorter than under an overcast sky.
3) The maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km. Range ambiguities have to be resolved by multiple-time-around processing.
4) Effective FOV 75°, additional roll angle $\pm 5^\circ$.
5) If the laser beam hits, in part, more than one target, the laser's pulse power is split accordingly. Thus the achievable range is reduced.

Minimum Range

Accuracy ^{7) 9)}

Precision ^{8) 9)}

Laser Pulse Repetition Rate ^{1) 10)}

Max. Effective Measurement Rate ¹⁾

Echo Signal Intensity

Laser Wavelength

Laser Beam Divergence

Laser Beam Footprint (Gaussian Beam Definition)

5 m

20 mm

15 mm

up to 1800 kHz

up to 1,500,000 meas./sec. (@ 1800 kHz PRR & 75° FOV)

for each echo signal, high-resolution 16 bit intensity information is provided

near infrared

0.35 mrad ¹¹⁾

35 mm @ 100 m, 175 mm @ 500 m, 350 mm @ 1000 m

7) Accuracy is the degree of conformity of a measured quantity to its actual (true) value.

8) Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result.

9) One sigma @ 150 m range under *RIEGL* test conditions.

10) User selectable.

11) Measured at the 1/e² points. 0.35 mrad corresponds to an increase of 35 mm of beam diameter per 100 m distance.

Scanner Performance

Scanning Mechanism

Scan Pattern

Field of View (selectable)

Scan Speed (selectable)

Angular Step Width $\Delta \vartheta$ (selectable)

between consecutive laser shots

Angle Measurement Resolution

Scan Sync (optional)

rotating polygon mirror

parallel scan lines

$\pm 37.5^\circ = 75^\circ$

40 - 400 lines/sec

$0.002^\circ \leq \Delta \vartheta \leq 0.24^\circ$ ^{12) 13)}

0.001°

scanner rotation synchronization

Data Interfaces

Configuration

Scan Data Output

GNSS Interface

External Camera

External IMU & GNSS

LAN 10/100/1000 Mbit/sec, WLAN

LAN 10/100/1000 Mbit/sec

Serial RS-232 interface for data string with GNSS-time information,

TTL input for 1PPS synchronization pulse

4x power, RS-232, 1pps, trigger, exposure, TTL input/output

combined connector with power supply and

signal interface to external IMU & GNSS

General Technical Data

Power Supply Input Voltage / Consumption ¹⁴⁾

Main Dimensions (L x W x H)

Weight

Humidity

Protection Class

Max. Flight Altitude (operating & not operating)

Temperature Range

11 - 34 V DC / typ. 60 W

292 mm x 164 mm x 185 mm (without IMU/GNSS)

380 mm x 164 mm x 185 mm (with IMU/GNSS)

≤ 4.1 kg (without IMU/GNSS), ≤ 4.9 kg (with IMU/GNSS)

max. 80 % non condensing @ 31°C

IP64, dust and splash-proof

18 500 ft (5 600 m) above MSL (Mean Sea Level)

-10°C up to +40°C (operation) / -20°C up to +50°C (storage)

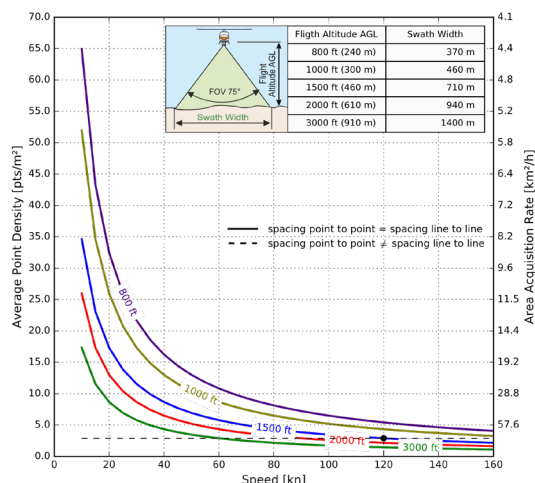
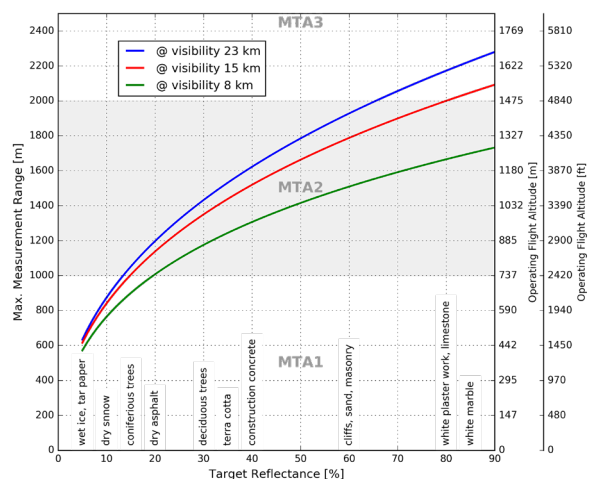
12) The angular step width depends on the selected laser PRR.
13) The maximum angular step width is limited by the maximum scan rate.

14) without external IMU/GNSS

to be continued at page 6

Maximum Measurement Range & Point Density *RIEGL VUX®-240*

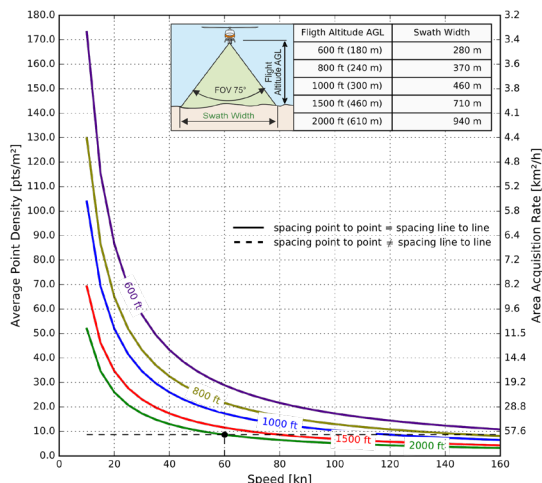
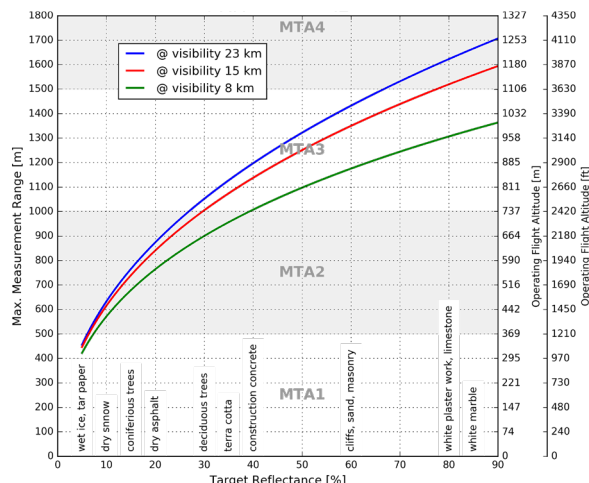
PRR = 150 kHz



Example: VUX-240 at 150,000 pulses/sec, laser power level 100%
Altitude = 1,500 ft AGL, Speed 120 kn

Results: Point Density ~ 3 pts/m²

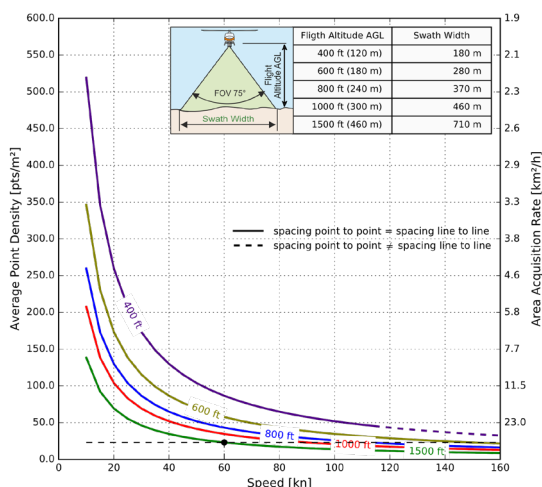
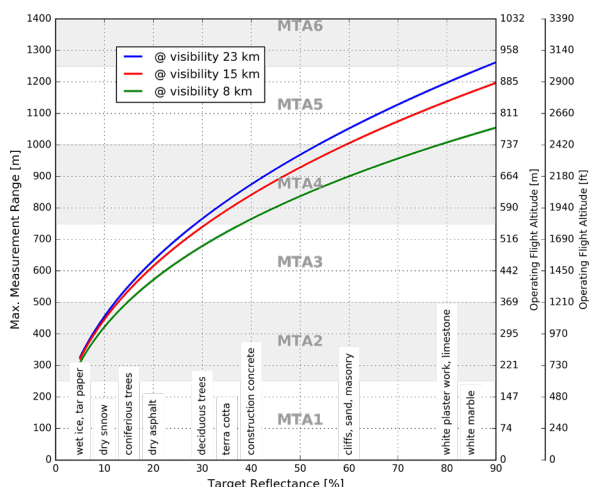
PRR = 300 kHz



Example: VUX-240 at 300,000 pulses/sec, laser power level 100%
Altitude = 2,000 ft AGL, Speed 60 kn

Results: Point Density ~ 9 pts/m²

PRR = 600 kHz



Example: VUX-240 at 600,000 pulses/sec, laser power level 100%
Altitude = 1,500 ft AGL, Speed 60 kn

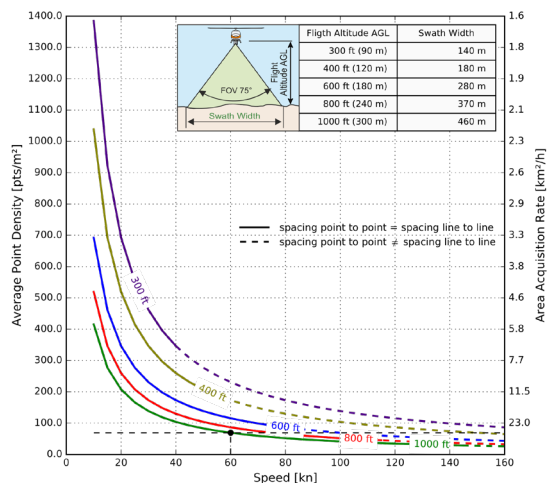
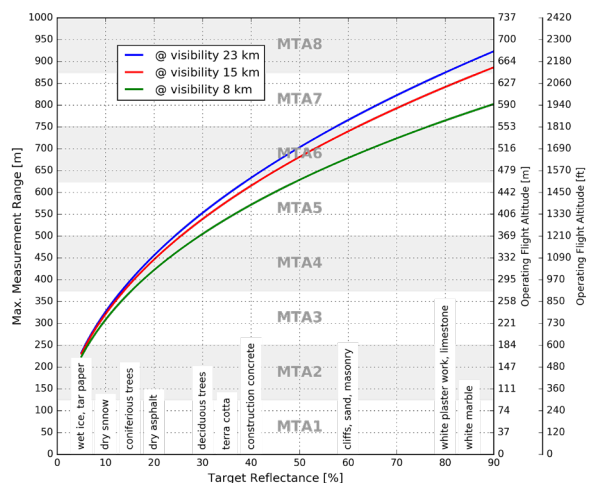
Results: Point Density ~ 22 pts/m²

The following conditions are assumed for the Operating Flight Altitude AGL

- ambiguity resolved by multiple-time-around (MTA) processing
- roll angle $\pm 5^\circ$
- target size \geq laser footprint
- average ambient brightness
- operating flight altitude given at a FOV 75°

Maximum Measurement Range & Point Density *RIEGL VUX®-240*

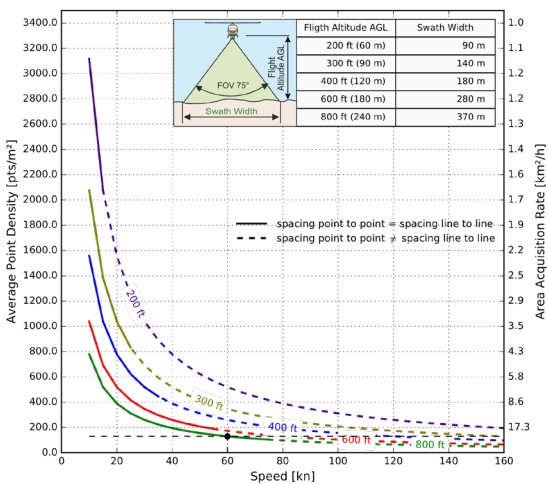
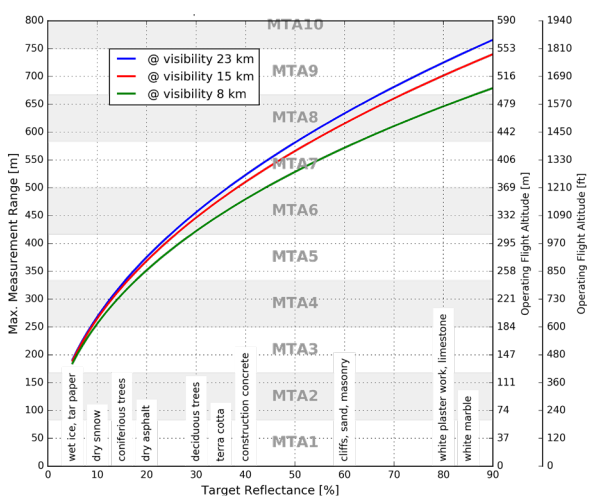
PRR = 1200 kHz



Example: VUX-240 at 1,200,000 pulses/sec, laser power level 100%
Altitude = 1,000 ft AGL, Speed 60 kn

Results: Point Density ~ 60 pts/m²

PRR = 1800 kHz



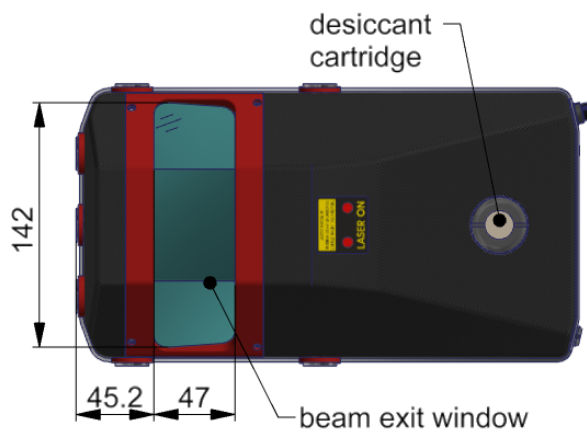
Example: VUX-240 at 1,800,000 pulses/sec, laser power level 100%
Altitude = 800 ft AGL, Speed 60 kn

Results: Point Density ~ 120 pts/m²

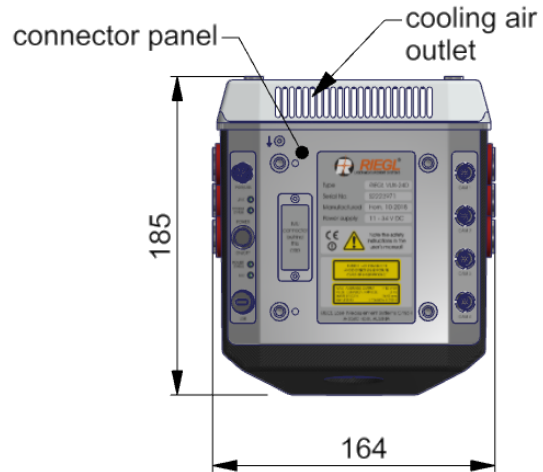
The following conditions are assumed for the Operating Flight Altitude AGL

- ambiguity resolved by multiple-time-around (MTA) processing
- roll angle $\pm 5^\circ$
- target size \geq laser footprint
- average ambient brightness
- operating flight altitude given at a FOV of 75°

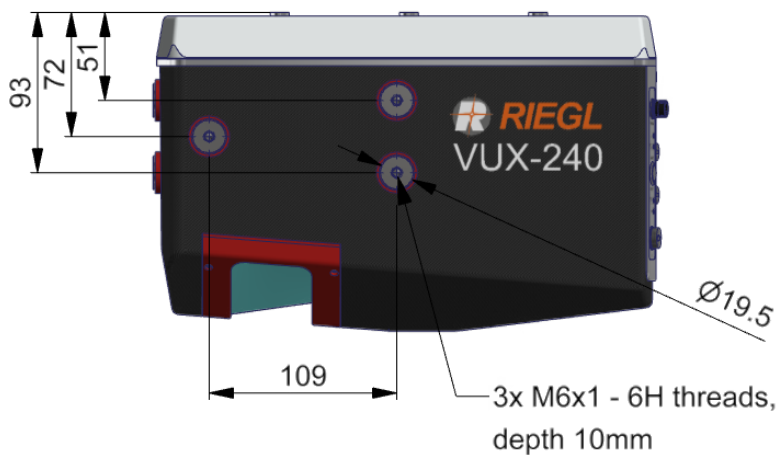
bottom view



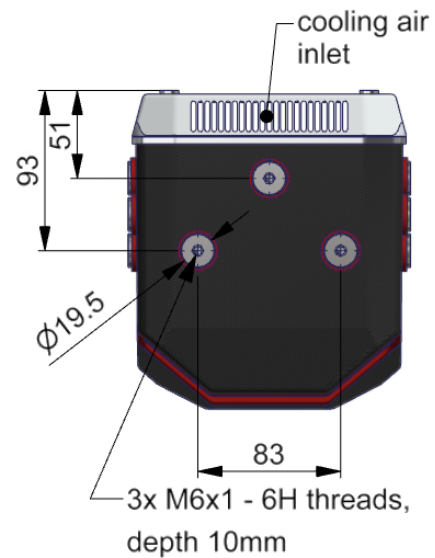
rear view



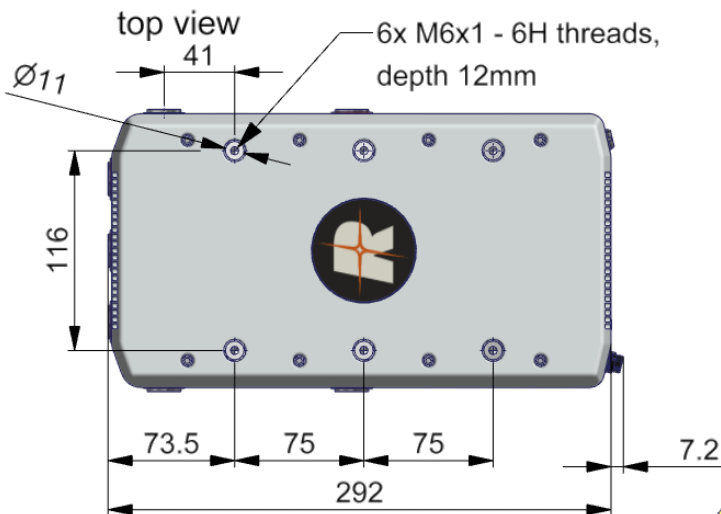
side view



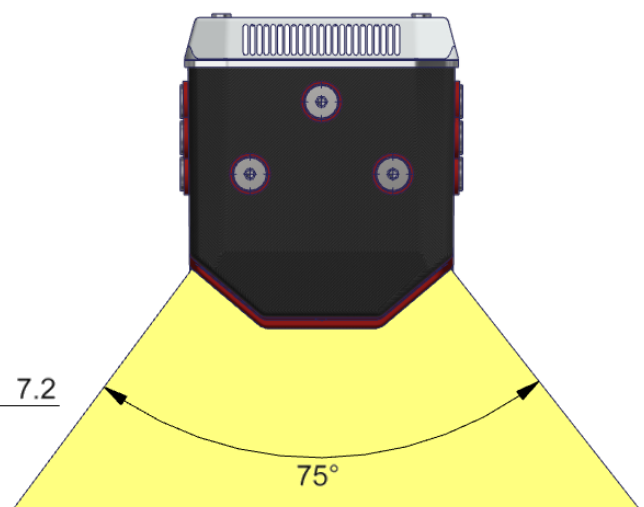
front view



top view



front view with FOV



all dimensions in mm

Technical Data *RIEGL* VUX[®]-240 (continued)

Data Storage

Internal Data Storage
Memory Card Slot¹⁾

Solid State Disc SSD, 1TByte
for CFAST^{® 2)} memory card 120 GByte (can be upgraded to 256 GByte)

1) applies to IMU APX-20 UAV only

2) CFAST is a registered trademark of CompactFlash Association

External IMU & GNSS (optional)

IMU Accuracy⁴⁾

Roll, Pitch

Heading

IMU Sampling Rate

Position Accuracy (typ.)

horizontal

vertical

recommended: Applanix APX-20 UAV³⁾

0.015°

0.035°

200 Hz

< 0.05m

< 0.1 m

3) See technical details at the according Applanix datasheet.

4) Accuracy specifications for post-processed data.



RIEGL VUX-240 equipped with APX-20 UAV

RIEGL VUX[®]-240 UAV Platform Integration (optional)



RiCOPTER with *RIEGL* VUX-240 LiDAR Sensor,
APX-20 UAV and nadir RGB camera fully integrated



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